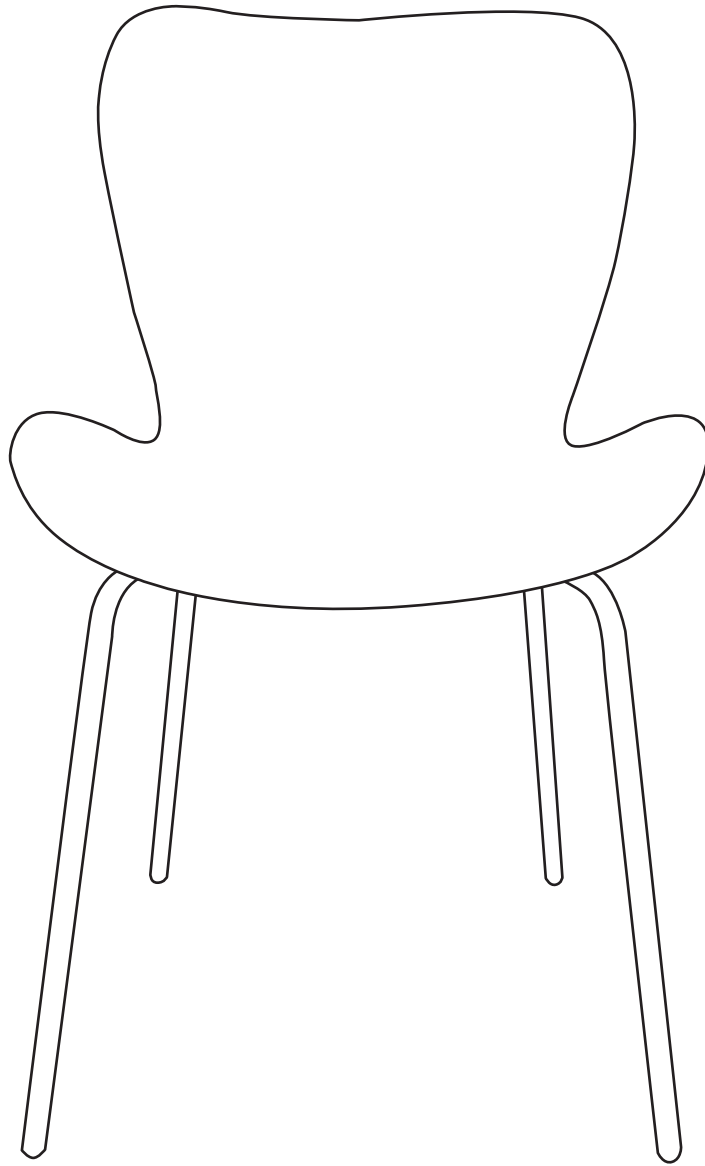


Batilda

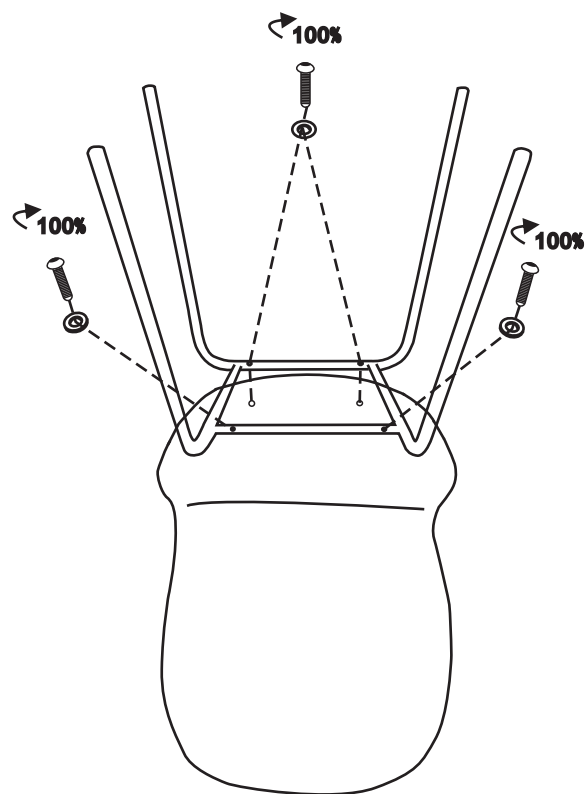




The diagram illustrates a three-armed robot. The central body is labeled A. The three arms are labeled B. Each arm has a gripper (C) and a sensor (E). The grippers are shown in a 80% open position. The sensor is shown in a 80% closed position.

A simple line drawing of a person sitting on a chair, viewed from the side. The person is sitting upright with their back straight, arms resting on their thighs, and feet flat on the floor. The chair has a high back and four legs.

3.



4.

